Annotation

For the period of scientificresearchin theen terprise of the State Enterprise "Kiev Scientific ResearchInstituteof Hydraulic Devices".

There port on research practice includ essections: "Krypton MUV 1 Infiniteunderwatervehicle", "Krypton AUV Autonomous Underwater Device", and "PTM Device". Choice of measuring devic essuchas: moist ure and temperature sensor, speedsensor, ultrasonic rangefinder, immersion gauge, engine, control device, lighting. Development ofin telligent control system. Development of the hard ware system. Software development. Choosing a GPS data channel for location and spatial signal for datameta data.

The purpose of the work is to analy zeand study underwater microrobots.

As a result of the implementation of scientific practice, recommendations were made or theuse of under watermicrorobots to study the underwaterworld.